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☐	L10	('6852107' |'6728599' |'6436107' |'6063095' |'6007550' |'5971976' |'US20030135203A' |'EP 1290982A' |'US 5971976A' |'US 5762458A')!.ABPN1,NRPN,PN,TBAN,WKU.	13
☐	L9	(5971976 | 6063095 | 6007550 | 6436107 | 6728599 | 6852107 | 10/067730).pn.	13
☐	L8	L5 and camera	9
☐	L7	L5 and camera and conferencing	1
☐	L6	L5 and robot$6	4
☐	L5	patient environment and operator	108
☐	L4	patient environment and operator environment	0
☐	L3	patient environment and operator environment and video and audio	0
☐	L2	patient environment and operator environment and video and audio and control$3 and robot6	0
☐	L1	robot$6 and three wheel and computer and camera	65

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☐	L4	network and L3	157
☐	L3	station and mobile robot	443
☐	L2	remore station and mobile robot	0
☐	L1	parallel remore station and mobile robot	0

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☐	L8	(5971976 | 6063095 | 6007550 | 6436107 | 6728599 | 6852107 | 10/067730).pn.	13
☐	L7	L4 and camera	9
☐	L6	L4 and camera and conferencing	1
☐	L5	L4 and robot$6	4
☐	L4	patient environment and operator	107
☐	L3	patient environment and operator environment	0
☐	L2	patient environment and operator environment and video and audio	0
☐	L1	patient environment and operator environment and video and audio and control$3 and robot6	0

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☐	L3	robot$6 and L2	189
☐	L2	camera and L1	276
☐	L1	minimally invasive surgery and remote	596

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1 **Robotics in minimally invasive surgery**
Davies, B.;
Through the Keyhole: Microengineering in Minimally Invasive Surgery, IEE Colloquium on , 6 Jun 1995
Pages:5/1 - 5/2

[Abstract]   [PDF Full-Text (124 KB)]   **IEE CNF**

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2 **Hyper redundant miniature manipulator "Hyper Finger" for remote minimally invasive surgery in deep area**
Ikuta, K.; Hasegawa, T.; Daifu, S.;
Robotics and Automation, 2003. Proceedings. ICRA '03. IEEE International Conference on , Volume: 1 , 14-19 Sept. 2003
Pages:1098 - 1102 vol.1

[Abstract]   [PDF Full-Text (388 KB)]   **IEEE CNF**

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3 **A force reflective master-slave system for minimally invasive surgery**
Tavakoli, M.; Patel, R.V.; Moallem, M.;
Intelligent Robots and Systems, 2003. (IROS 2003). Proceedings. 2003 IEEE/RSJ International Conference on , Volume: 4 , 27-31 Oct. 2003
Pages:3077 - 3082 vol.3

[Abstract]   [PDF Full-Text (720 KB)]   **IEEE CNF**

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4 **Dual use applications of Wright Laboratory Avionics Technologies to computer assisted minimally invasive surgery (CAMIS)**
Williams, R.;
Aerospace and Electronics Conference, 1994. NAECON 1994., Proceedings of the IEEE 1994 National , 23-27 May 1994
Pages:1248 - 1251 vol.2

[Abstract]   [PDF Full-Text (276 KB)]   **IEEE CNF**

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5 Controlling miniature robotic systems in minimally invasive surgery
Wapler, M.; Neugebauer, J.;
Intelligent Robots and Systems '94. 'Advanced Robotic Systems and the Real
World', IROS '94. Proceedings of the IEEE/RSJ/GI International Conference
on , Volume: 1 , 12-16 Sept. 1994
Pages:711 - 716 vol.1

[Abstract]   [PDF Full-Text (364 KB)]   **IEEE CNF**

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6 Minimally invasive surgery and technology
Fiennes, A.G.T.W.;
Technology in Medicine: Has Practice Met the Promise? (Digest No. 1996/177), IEE
Colloquium on , 7 Oct. 1996
Pages:2/1 - 2/3

[Abstract]   [PDF Full-Text (236 KB)]   **IEE CNF**

**7 Force controlled and teleoperated endoscopic grasper for minimally
invasive surgery-experimental performance evaluation**
Rosen, J.; Hannaford, B.; MacFarlane, M.P.; Sinanan, M.N.;
Biomedical Engineering, IEEE Transactions on , Volume: 46 , Issue: 10 , Oct. 1999
Pages:1212 - 1221

[Abstract]   [PDF Full-Text (444 KB)]   **IEEE JNL**

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8 Applications of micromechatronics in minimally invasive surgery
Tendick, F.; Sastry, S.S.; Fearing, R.S.; Cohn, M.;
Mechatronics, IEEE/ASME Transactions on , Volume: 3 , Issue: 1 , March 1998
Pages:34 - 42

[Abstract]   [PDF Full-Text (144 KB)]   **IEEE JNL**

**9 Surgery benefits from defense technology: dual use applications of
Wright Laboratory Avionics technologies to Computer Assisted Minimally
Invasive Surgery (CAMIS)**
Williams, R.; Leonard, J.;
Aerospace and Electronic Systems Magazine, IEEE , Volume: 9 , Issue: 10 , Oct.
1994
Pages:3 - 6

[Abstract]   [PDF Full-Text (324 KB)]   **IEEE JNL**

**10 Application of combined methods of imaging in minimally invasive
surgery**
Cysewska-Sobusiak, A.R.; Sowier, A.; Skrzywanek, P.;
Engineering in Medicine and Biology Society, 2003. Proceedings of the 25th Annual
International Conference of the IEEE , Volume: 2 , 17-21 Sept. 2003
Pages:1043 - 1046 Vol.2

[Abstract]   [PDF Full-Text (488 KB)]   **IEEE CNF**

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11 A medical robotic assistant for minimally invasive surgery
*Munoz, V.F.; Vara-Thorbeck, C.; DeGabriel, J.G.; Lozano, J.F.; Sanchez-Badajoz,
E.; Garcia-Cerezo, A.; Toscano, R.; Jimenez-Garrido, A.;*
Robotics and Automation, 2000. Proceedings. ICRA '00. IEEE International
Conference on , Volume: 3 , 24-28 April 2000
Pages:2901 - 2906 vol.3

[Abstract]   [PDF Full-Text (560 KB)]   IEEE CNF

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12 Human-machine interfaces for minimally invasive surgery
Tendick, F.; Cavusoglu, M.C.;
Engineering in Medicine and Biology society, 1997. Proceedings of the 19th Annual
International Conference of the IEEE , Volume: 6 , 30 Oct.-2 Nov. 1997
Pages:2771 - 2776 vol.6

[Abstract]   [PDF Full-Text (604 KB)]   IEEE CNF

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13 Sensors and devices to enhance the performances of a minimally invasive surgery tool for replicating surgeon's haptic perception of the manipulated tissues
Scilingo, E.P.; De Rossi, D.; Bicchi, A.; Iacconi, P.;
Engineering in Medicine and Biology society, 1997. Proceedings of the 19th Annual
International Conference of the IEEE , Volume: 3 , 30 Oct.-2 Nov. 1997
Pages:961 - 964 vol.3

[Abstract]   [PDF Full-Text (276 KB)]   IEEE CNF

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14 Telemanipulator design for minimally invasive surgery
Lazeroms, M.; Jongkind, W.; Honderd, G.;
American Control Conference, 1997. Proceedings of the 1997 , Volume: 5 , 4-6
June 1997
Pages:2982 - 2986 vol.5

[Abstract]   [PDF Full-Text (468 KB)]   IEEE CNF

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15 An articulated manipulator for enhanced dexterity in minimally invasive surgery
Mukherjee, R.; Song, G.; Satava, R.;
Engineering in Medicine and Biology Society, 1996. Bridging Disciplines for
Biomedicine. Proceedings of the 18th Annual International Conference of the
IEEE , Volume: 1 , 31 Oct.-3 Nov. 1996
Pages:220 - 222 vol.1

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Pages:2982 - 2986 vol.5

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1 **An environment for the collaborative revision of digital theses**
Fernandez, L.; Sanchez, J.A.; Flores, A.;
Groupware, 2000. CRIWG 2000. Proceedings. Sixth International Workshop on , 18-20
Oct. 2000
Pages:150 - 153

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2 **Web component development for satellite imagery internet service system**
Jong-Hyun Park; Chung-Hyun Ahn; Kyoung-Ok Kim; Young-Kyu Yang;
Geoscience and Remote Sensing Symposium, 2001. IGARSS '01. IEEE 2001
International , Volume: 4 , 9-13 July 2001
Pages:1948 - 1950 vol.4

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3 **ZEUS: a CORBA framework for service location and creation**
Shankaran, N.; Klefstad, R.;
Applications and the Internet Workshops, 2004. SAINT 2004 Workshops. 2004
International Symposium on , 26-30 Jan. 2004
Pages:382 - 387

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4 **Adapting information presentation and retrieval through user modelling**
Bogonikolos, N.; Makris, C.; Tsakalidis, A.; Vassiliadis, B.;
Information Technology: Coding and Computing, 2001. Proceedings. International
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Pages:399 - 404

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5 **"ARCHIMIDES": an intelligent agent for adaptive-personalized navigation
within a WEB server**
Bogonikolos, N.; Fragoudis, D.; Likothanassis, S.;
System Sciences, 1999. HICSS-32. Proceedings of the 32nd Annual Hawaii International
Conference on , Volume: Track5 , 5-8 Jan. 1999
Pages:9 pp.

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6 **Techniques for developing and measuring high performance Web servers
over high speed networks**
Hu, J.C.; Mungee, S.; Schmidt, D.C.;
INFOCOM '98. Seventeenth Annual Joint Conference of the IEEE Computer and
Communications Societies. Proceedings. IEEE , Volume: 3 , 29 March-2 April 1998
Pages:1222 - 1231 vol.3

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7 Measuring the impact of event dispatching and concurrency models on Web server performance over high-speed networks
Hu, J.C.; Pyarali, I.; Schmidt, D.C.;
Global Telecommunications Conference, 1997. GLOBECOM '97., IEEE , Volume: 3 , 3-8 Nov. 1997
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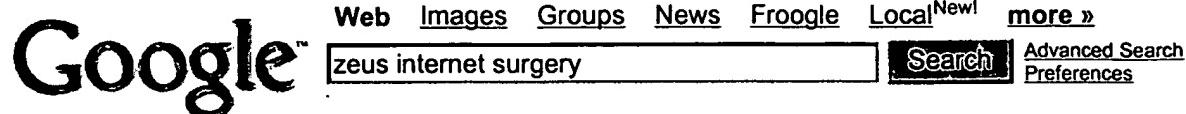
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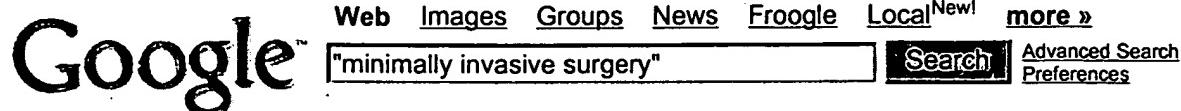
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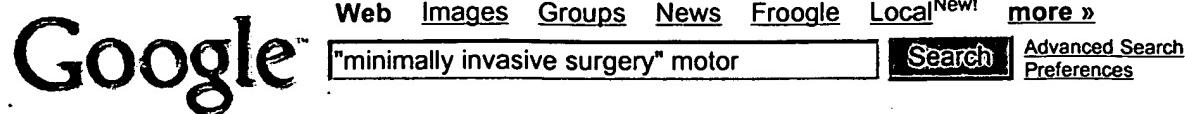
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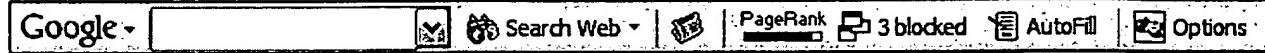
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